

Three phase AC motor soft starter



Benefits

- **Easy to use.** RSGT is equipped with a self-learning algorithm that automatically adjusts the start parameters to optimise the motor starts and stops.
- **Fast installation and set-up.** Only 3 settings are required (FLC, ramp-up and ramp-down).
- **Compact dimensions.** 12 - 25 Arms in 45mm wide housing, 32 - 55 Arms in 75mm wide housing, 70 - 90 Arms in 120mm housing.
- **Integrated protection.** Diagnostic functions provide additional protection. RSGT is also equipped with an overload protection (Class 10).
- **Less stresses on motors.** The control on all the 3-phases results in better current reduction and no current imbalance during motor start.
- **Torque control during ramp-down.** Smoother deceleration of the load.
- **Load condition monitoring.** The RSGT is equipped with a Modbus/RTU communication port (2-wire connection).
- **Guided model selection.** Easy to use selection tool to select the appropriate soft starter model depending on the application type.

Description

RSGT is an extremely compact and easy to use 3-phase soft starter for AC induction motors rated up to 90 Arms. The starting parameters can be easily set-up through 3 selector switches.

The integrated motor overload protection (Class 10) and Modbus communication result in a higher installation flexibility.

Applications

RSGT soft starters are the ideal solution for 3-phase fixed speed AC induction motor applications where there is the need to reduce the starting current and/or minimise stresses on the motor during start and stop.

The RSGT offers a number of integrated diagnostic functions that can replace additional components inside the electrical panel.

Typical applications include: compressors, pumps and fans.

Main functions

- Soft starting and soft stopping of AC motors
- Integrated electronic overload protection (Class 10)
- Wrong phase sequence detection
- Torque control during ramp-down
- Top of ramp and alarm relay indication
- Dry run detection for pumps
- Serial communication (Modbus) over RS485

References

► Order code



Enter the code entering the corresponding option instead of

| Code | Option | Description | Notes |
|--------------------------|--------|---|--------------------------------------|
| R | - | | |
| S | - | Soft starter | |
| G | - | General purpose | |
| T | - | Three phase control | |
| <input type="checkbox"/> | 40 | 220 – 400 VAC +10% -15% operational voltage (Ue) | |
| <input type="checkbox"/> | 60 | 220 – 600 VAC +10% -15% operational voltage (Ue) | |
| <input type="checkbox"/> | 12 | 12 Arms | Rated operational current @ 40 °C |
| <input type="checkbox"/> | 16 | 16 Arms | |
| <input type="checkbox"/> | 25 | 25 Arms | |
| <input type="checkbox"/> | 32 | 32 Arms | |
| <input type="checkbox"/> | 45 | 45 Arms | |
| <input type="checkbox"/> | 55 | 55 Arms | |
| <input type="checkbox"/> | 70 | 70 Arms | |
| <input type="checkbox"/> | 90 | 90 Arms | |
| <input type="checkbox"/> | E0 | 110 - 400 VAC (+10%, - 15%) control voltage (Uc) Supply voltage: internally supplied | RSGT40 models only |
| <input type="checkbox"/> | F0 | 24 VAC/DC (+10%, - 10%) control voltage (Uc) Supply voltage: internally supplied | |
| <input type="checkbox"/> | FF | 24 VAC/DC (+10%, - 10%) control/supply voltage Supply voltage: externally supplied | |
| <input type="checkbox"/> | GG | 100 - 240 VAC (+10%, - 15%) control/supply voltage Supply voltage: externally supplied | |
| V | - | | |
| 1 | - | With integrated motor overload protection (Class 10) | |
| <input type="checkbox"/> | 0 | No PTC | RSGT 45 mm models |
| <input type="checkbox"/> | 1 | With PTC | RSGT 75/120 mm models |
| <input type="checkbox"/> | - | No fan | RSGT 45 mm models |
| <input type="checkbox"/> | 0 | | RSGT 32 Arms models only |
| <input type="checkbox"/> | 1 | With fan | RSGT 45 Arms to RSGT 90 Arms models |
| <input type="checkbox"/> | - | Without communication | |
| <input type="checkbox"/> | C | With Modbus communication | |

 **Selection guide**

| | | Operational voltage: 400 VAC | | Operational voltage: 600 VAC | |
|---------------------------------------|---------------|--------------------------------------|------------------------------------|---|---|
| Rated operational current (Ie) | Modbus | Control voltage 110 - 400 VAC | Control voltage 24 VAC / DC | Control/supply voltage 100 - 240 VAC | Control/supply voltage 24 VAC / DC |
| 12 Arms | No | RSGT4012E0V10 | RSGT4012F0V10 | RSGT6012GGV10 | RSGT6012FFV10 |
| 16 Arms | | RSGT4016E0V10 | RSGT4016F0V10 | RSGT6016GGV10 | RSGT6016FFV10 |
| 25 Arms | | RSGT4025E0V10 | RSGT4025F0V10 | RSGT6025GGV10 | RSGT6025FFV10 |
| 12 Arms | Yes | RSGT4012E0V10C | RSGT4012F0V10C | RSGT6012GGV10C | RSGT6012FFV10C |
| 16 Arms | | RSGT4016E0V10C | RSGT4016F0V10C | RSGT6016GGV10C | RSGT6016FFV10C |
| 25 Arms | | RSGT4025E0V10C | RSGT4025F0V10C | RSGT6025GGV10C | RSGT6025FFV10C |
| 32 Arms | | RSGT4032E0V110C | RSGT4032F0V110C | RSGT6032GGV110C | RSGT6032FFV110C |
| 45 Arms | | RSGT4045E0V111C | RSGT4045F0V111C | RSGT6045GGV111C | RSGT6045FFV111C |
| 55 Arms | | RSGT4055E0V111C | RSGT4055F0V111C | RSGT6055GGV111C | RSGT6055FFV111C |
| 70 Arms | | RSGT4070E0V111C | RSGT4070F0V111C | RSGT6070GGV111C | RSGT6070FFV111C |
| 90 Arms | | RSGT4090E0V111C | RSGT4090F0V111C | RSGT6090GGV111C | RSGT6090FFV111C |

 **Further reading**

| Information | Where to find it | QR |
|-----------------------------------|---|---|
| RSGT 45 mm instruction manual | http://cga.pub/?6ca01b |  |
| RSGT 75/120 mm instruction manual | http://cga.pub/?974b29 |  |
| RSGT troubleshooting guide | http://cga.pub/?11a31f |  |
| RSGT 45mm Monitor software | http://cga.pub/?afe4f5 |  |
| CAD drawings (RSGT 45 mm) | http://cga.pub/?bf3bed |  |
| CAD drawings (RSGT 75 mm) | http://cga.pub/?ee18e7 |  |
| CAD drawings (RSGT 120 mm) | http://cga.pub/?420858 |  |
| Modbus communication protocol | http://cga.pub/?8a5887 |  |


Selection guide and typical application settings

| Category | Type | Trip Class | Ramp-up setting [s] | Ramp-down setting [s] |
|--------------------|--------------------------------------|------------|---------------------|-----------------------|
| Compressors | Scroll compressor | 5 | 1 | 0 |
| | Screw compressor | 5 | 2 to 5 | 0 |
| | Piston compressor | 5 | 2 | 0 |
| | Centrifugal compressor | 10 | 10 | 0 |
| Pumps | Hydraulic pump | 5 | 2 | 0 |
| | Centrifugal pump (start time <10sec) | 5 | 5 to 10 | 10 |
| | Centrifugal pump (start time >10sec) | 10 | 10 to 20 | 15 |
| | Piston pump | 10 | 5 to 10 | 0 |
| Fans | Centrifugal fan (<0.5m diameter) | 10 | 5 to 10 | 0 |
| | Centrifugal fan (>0.5m diameter) | 20 | 15 to 20 | 0 |
| | Vacuum blowers | 10 | 5 to 10 | 0 |
| Feeders | Screw feeder | 10 | 2 to 10 | 0 |
| | Auger | 10 | 5 to 10 | 0 |
| Rotating machinery | Agitators | 10 | 5 to 15 | 0 |
| | Mixers | 10 | 5 to 10 | 0 |
| | Saws (<0.5 m diameter) | 10 | 5 to 10 | 5 |
| | Saws (>0.5 m diameter) | 20 | 15 to 20 | 10 |
| | Grinder | 20 | 15 to 20 | 0 |
| | Crusher | 30 | 20 | 0 |
| | Conveyors | 10 | 5 to 10 | 5 |

Note: when using the RSGT on high inertia loads (Trip Class 20, 30) ensure that enough time is left between starts to allow the RSGT to cool down.

For Trip Class 20 and Class 30 applications we recommend the use of an external overload protection due to the higher FLC setting that is required on RSGT. The FLC setting for Class 20 and Class 30 applications needs to be set to a higher value with respect to the motor FLC in order not to trip the electronic motor overload protection available on the RSGT soft starters.


Selection guide (220 - 400 VAC)

| Motor FLC [A] | Motor HP ratings | | Motor kW ratings | | Trip class 5 | Trip class 10 | Trip class 20 | Trip Class 30 |
|---------------|------------------|---------|------------------|---------|--------------|---------------|---------------|---------------|
| | @ 230 V | @ 400 V | @ 230 V | @ 400 V | | | | |
| 1.8 | 1/3 | 1 | 0.25 | 0.75 | RSGT4012.. | RSGT4012.. | RSGT4012.. | RSGT4012.. |
| 2.6 | 1/2 | 1.5 | 0.37 | 1.1 | RSGT4012.. | RSGT4012.. | RSGT4012.. | RSGT4012.. |
| 3.4 | 3/4 | 2 | 0.56 | 1.5 | RSGT4012.. | RSGT4012.. | RSGT4012.. | RSGT4012.. |
| 5 | 1.5 | 3 | 1.1 | 2.2 | RSGT4012.. | RSGT4012.. | RSGT4012.. | RSGT4012.. |
| 6 | 1.5 | 4 | 1.1 | 3 | RSGT4012.. | RSGT4012.. | RSGT4012.. | RSGT4012.. |
| 9 | 2 | 5.5 | 1.5 | 4 | RSGT4012.. | RSGT4012.. | RSGT4016.. | RSGT4025.. |
| 12 | 4 | 7.5 | 3 | 5.5 | RSGT4012.. | RSGT4012.. | RSGT4025.. | RSGT4025.. |
| 16 | 5.5 | 10 | 4 | 7.5 | RSGT4016.. | RSGT4016.. | RSGT4032.. | RSGT4045.. |
| 22 | 7.5 | 15 | 5.5 | 11 | RSGT4025.. | RSGT4025.. | RSGT4045.. | RSGT4045.. |
| 30 | 10 | 20 | 7.5 | 15 | RSGT4032.. | RSGT4032.. | RSGT4055.. | RSGT4070.. |
| 37 | 10 | 25 | 7.5 | 18 | RSGT4045.. | RSGT4045.. | RSGT4090.. | RSGT4090.. |
| 45 | 15 | 30 | 11 | 22 | RSGT4045.. | RSGT4045.. | RSGT4090.. | RSGT4090.. |
| 55 | 20 | 40 | 15 | 30 | RSGT4055.. | RSGT4055.. | RSGT4090.. | RSGT4090.. |
| 70 | 25 | 50 | 18 | 37 | RSGT4070.. | RSGT4070.. | - * | - * |
| 85 | 30 | 60 | 22 | 45 | RSGT4090.. | RSGT4090.. | - * | - * |

- * Contact Carlo Gavazzi representative for further information.

- Option "E0": 110 - 400 VAC or option "F0": 24 VAC/DC.


Selection guide (480 - 600 VAC)

| Motor FLC [A] | Motor HP ratings | | Motor kW ratings | | Trip class 5 | Trip class 10 | Trip class 20 | Trip class 30 |
|---------------|------------------|--------|------------------|--------|--------------|---------------|---------------|---------------|
| | @ 480V | @ 600V | @ 480V | @ 600V | | | | |
| 1.6 | 3/4 | 1 | 0.56 | 0.75 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 2.4 | 1 | 1.5 | 0.75 | 1.1 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 3 | 1.5 | 2 | 1.1 | 1.5 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 3.9 | 2 | 3 | 1.5 | 2.2 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 5 | 3 | 4 | 2.2 | 3 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 6 | 3 | 5 | 2.2 | 3.7 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 9 | 5 | 7.5 | 3.7 | 5.5 | RSGT6012.. | RSGT6012.. | RSGT6012.. | RSGT6012.. |
| 11 | 7.5 | 10 | 5.5 | 7.5 | RSGT6012.. | RSGT6012.. | RSGT6016.. | RSGT6025.. |
| 16 | 10 | 15 | 7.5 | 11 | RSGT6016.. | RSGT6016.. | RSGT6032.. | RSGT6032.. |
| 22 | 15 | 20 | 11 | 15 | RSGT6025.. | RSGT6025.. | RSGT6045.. | RSGT6045.. |
| 27 | 20 | 25 | 15 | 18 | RSGT6032.. | RSGT6032.. | RSGT6055.. | RSGT6055.. |
| 32 | 20 | 30 | 15 | 22 | RSGT6032.. | RSGT6032.. | RSGT6070.. | RSGT6070.. |
| 41 | 30 | 40 | 22 | 30 | RSGT6045.. | RSGT6045.. | RSGT6070.. | RSGT6070.. |
| 52 | 40 | 50 | 30 | 37 | RSGT6055.. | RSGT6055.. | RSGT6090.. | - * |
| 70 | 50 | 60 | 37 | 45 | RSGT6070.. | RSGT6070.. | - * | - * |
| 85 | 60 | 75 | 45 | 55 | RSGT6090.. | RSGT6090.. | - * | - * |

- * Contact Carlo Gavazzi representative for further information.

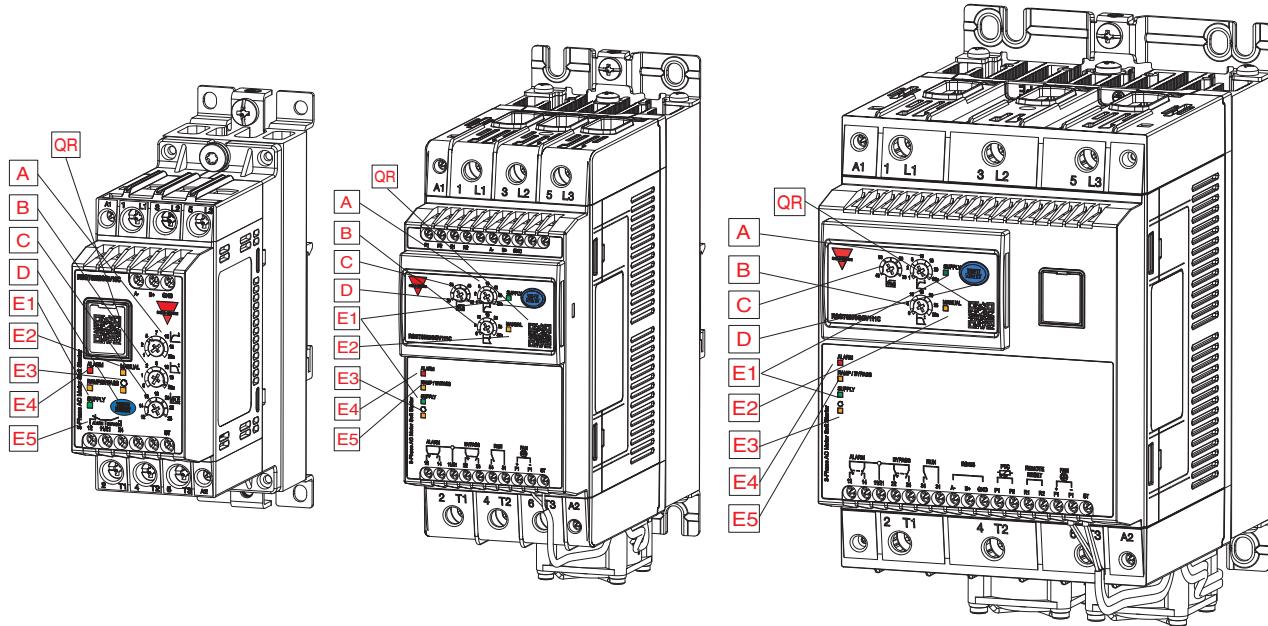
- Option "GG": 100 - 240 VAC or option "FF": 24 VAC/DC.

Caution: the actual motor Amps may be higher or lower than the average values listed above. We suggest to use the actual motor current as listed on the motor nameplate. Use this table as a guide only.

 **Carlo Gavazzi compatible components**

| Purpose | Component name/code | Notes |
|--|----------------------------|--|
| PC interface cable (Isolated USB to TTL cable) | RS-USB | For RSGT..12..V10 to RSGT..25..V10 |
| Finger guards | RFCGX6 | 6 pcs per box |
| Cooling fan | RFAN-75-40 12 X1 | For RSGT 75/120mm models only Rated voltage: 12 VDC Power consumption: 0.6 W |

Structure



| Element | Component | Function |
|-----------|-------------------------|---|
| A | Ramp-up time selector | Sets the desired motor starting time. |
| B | Ramp-down time selector | Sets the desired motor stopping time. |
| C | FLC selector | Sets the motor full load current (FLC). The FLC setting is used by the RSGT for the overload protection and for the maximum current allowed during motor start. |
| D | Test/Reset | Simulate overload alarm (press for 1 sec when RSGT is in Idle state) * The alarm recovery mode needs to be set to manual Set Manual/Automatic alarm recovery mode (press for 5 sec when RSGT is in Idle state) Reset alarms (press for <1sec when the RSGT is in alarm mode and alarm recovery mode is manual) Enable/disable phase sequence protection (press for 10 sec when RSGT is in Idle state) Enable/disable dry run function (press for 3 sec when RSGT is in Idle state) Enable/disable overload function (press for 8 sec when RSGT is in Idle state) Note: While the Test/Reset button is pressed the LED E5 will start flashing with a frequency of 1 Hz (1/sec) in order to help the user count the number of seconds elapsed. |
| E1 | LED indicators | Supply. Indicates that the RSGT supply is ON. |
| E2 | LED indicators | Manual. Indicates the alarm reset mode. Manual reset mode - LED ON, Auto reset mode - LED OFF (Factory default setting: Auto, LED OFF) |
| E3 | LED indicators | Phase sequence. Indicates if the wrong phase sequence protection is enabled (LED OFF) or disabled (LED ON). (Factory default setting: Enabled, LED OFF) |
| E4 | LED indicators | Alarm. Indicates that the RSGT is in alarm. The number of flashes indicates the alarm type. |
| E5 | LED indicators | Ramping/bypass. Indicates whether RSGT is in ramping (flashing) or bypass (fully ON). Note: Ramping (no HP): 2 Hz flashing. Ramping (with HP): 10 Hz flashing. |
| QR | QR code | Scan to link to troubleshooting guide. |

Mode of operation

The RSGT series of soft starters works on two distinct self-learning algorithms depending on the ramp-up time settings.

| Ramp-up | Mode of operation |
|-----------------------------|--|
| 1 or 2 seconds | <ul style="list-style-type: none"> When the ramp-up selector is in position 1 or 2, the RSGT will follow a self-learning current limit algorithm. As soon as A1-A2 (or ST for RSGT60 models) control voltage signal is applied, the RSGT will start to ramp-up the motor. At the very first start the current limit will be 4 x FLC setting. In the subsequent starts, the RSGT will automatically adjust the current limit setting to maintain the motor start time as close as possible to the ramp-up time setting. |
| ≥ 5 seconds | <ul style="list-style-type: none"> When the ramp-up selector is in position 5 or above, the RSGT will follow a self-learning current ramp algorithm. The RSGT will start with a set of default parameters for starting torque. Depending on the ramp-up time setting, the RSGT will apply a current ramp algorithm to start the motor as close as possible to the set ramp-up time. During the motor start, the current will be limited to a maximum of 3.5 x FLC setting. In the subsequent starts, the RSGT will continue to adjust the starting parameters of initial torque and current ramp to ensure that the motor is started as close as possible to the set ramp-up time. |
| HP mode of operation | <ul style="list-style-type: none"> During the ramp-up sequence, the RSGT will check if the motor is rotating. If the RSGT detects that the motor is in locked rotor condition as soon as control is applied and/or the motor has not reached full speed at the set ramp-up time, it will trigger the HP function. This mode of operation is indicated via a faster flashing sequence on the ramping/bypass LED (E5). The maximum starting current during HP mode can reach: 4 x I_e for ramp-up setting of 1 or 2 seconds and 3.5 x I_e for ramp-up setting \geq 5 seconds. The RSGT will then go in bypass state as soon as it detects that the motor reached full speed. |

| Ramp-down | Mode of operation |
|--|--|
| 1 to 20 seconds (for RSGT 45mm) | <ul style="list-style-type: none"> During ramp-down, the RSGT works on a torque control algorithm for smoother stopping of the motor. As soon as the control voltage signal A1-A2 (or ST for RSGT 60 models) is removed, the RSGT will slow down the motor gradually according to the ramp-down setting. |
| 1 to 30 seconds (for RSGT 75/120mm) | <ul style="list-style-type: none"> The power semiconductors will be switched OFF as soon as the time (as per ramp-down setting) has elapsed unless there is a risk of exceeding the maximum temperature on the semiconductors. In such a case the RSGT will leave the motor to coast to stop. |
| 0 seconds | <ul style="list-style-type: none"> If the ramp-down selector is set to 0, the RSGT will leave the motor to coast to stop (no ramp-down). |

Settings

| | RSGT 45mm | RSGT 75mm | RSGT 120mm |
|---------------------------|--|--|--|
| Ramp-up time | 1 - 20 s | 1 - 30 s | 1 - 30 s |
| Ramp-down time | 0 - 20 s | 0 - 30 s | 0 - 30 s |
| Initial torque | Automatically determined by RSGT | | |
| FLC range settings | RSGT 12: 2 - 12 A RSGT 16: 6 - 16 A RSGT 25: 12 - 25 A | RSGT 32: 20 - 32 A RSGT 45: 32 - 45 A RSGT 55: 25 - 55 A | RSGT 70: 40 - 70 A RSGT 90: 60 - 90 A |

Features

General

| | RSGT 45 mm | RSGT 75 mm | RSGT 120 mm |
|-----------------------------|----------------|------------------|------------------|
| Material | | PA66 | |
| Assembly | | DIN or panel | |
| Protection grade | | IP20 | |
| Weight | 0.5 to 0.75 kg | 2.3 kg (approx.) | 3.5 kg (approx.) |
| Overvoltage category | | Cat. III | |

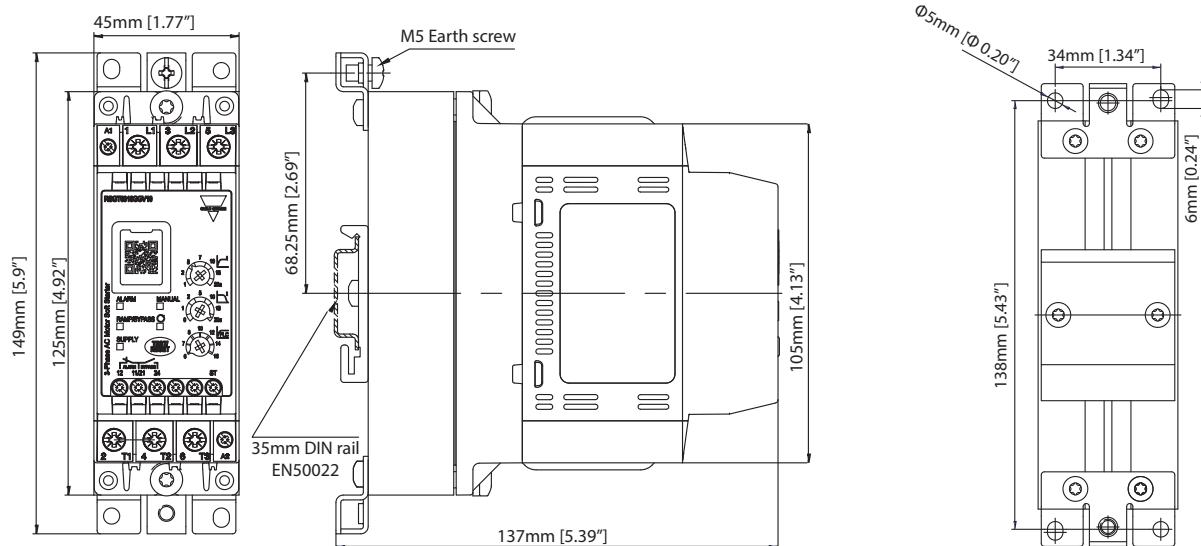


Fig. 1 RSGT 45mm: RSGT..12..to RSGT..16..

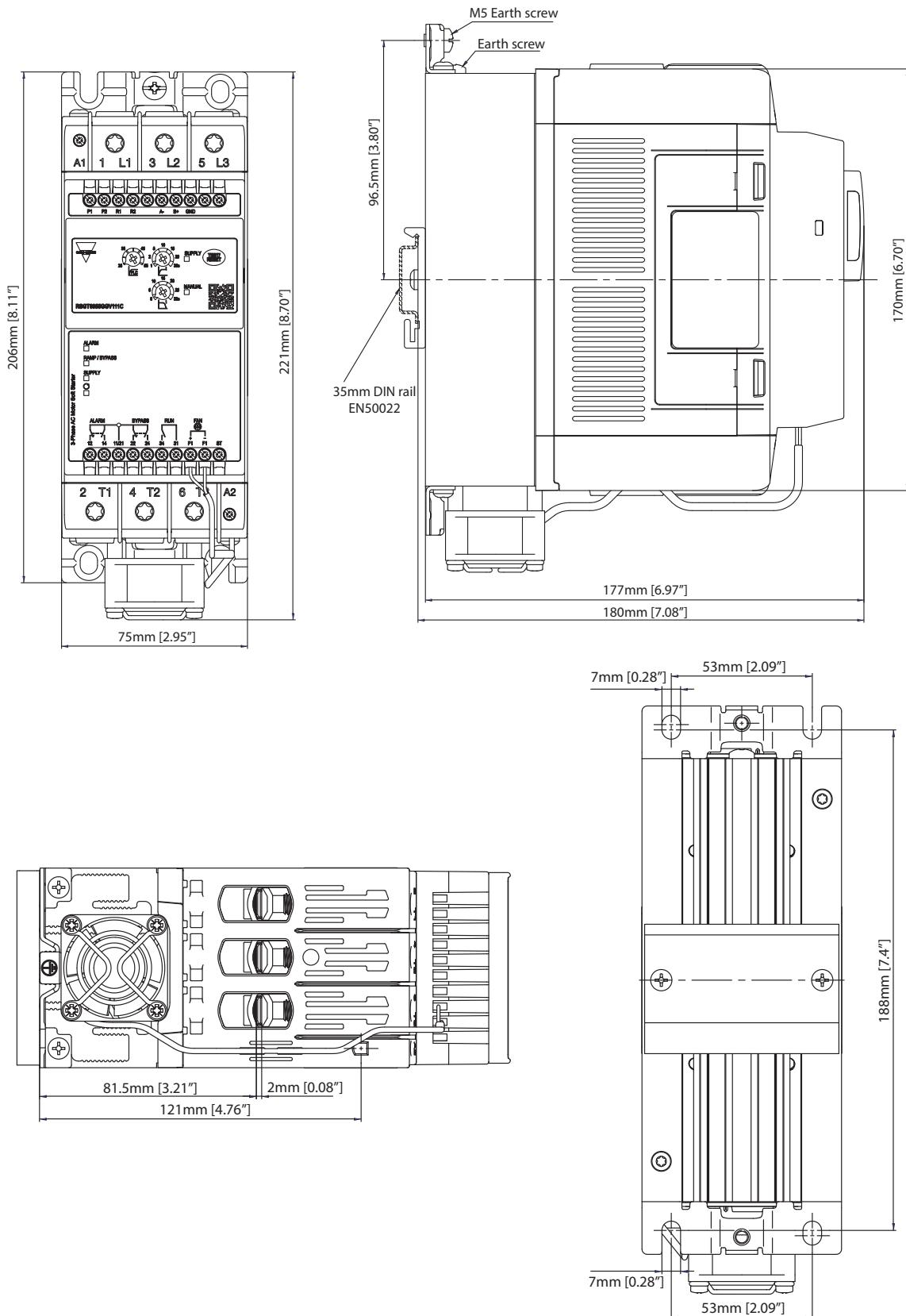
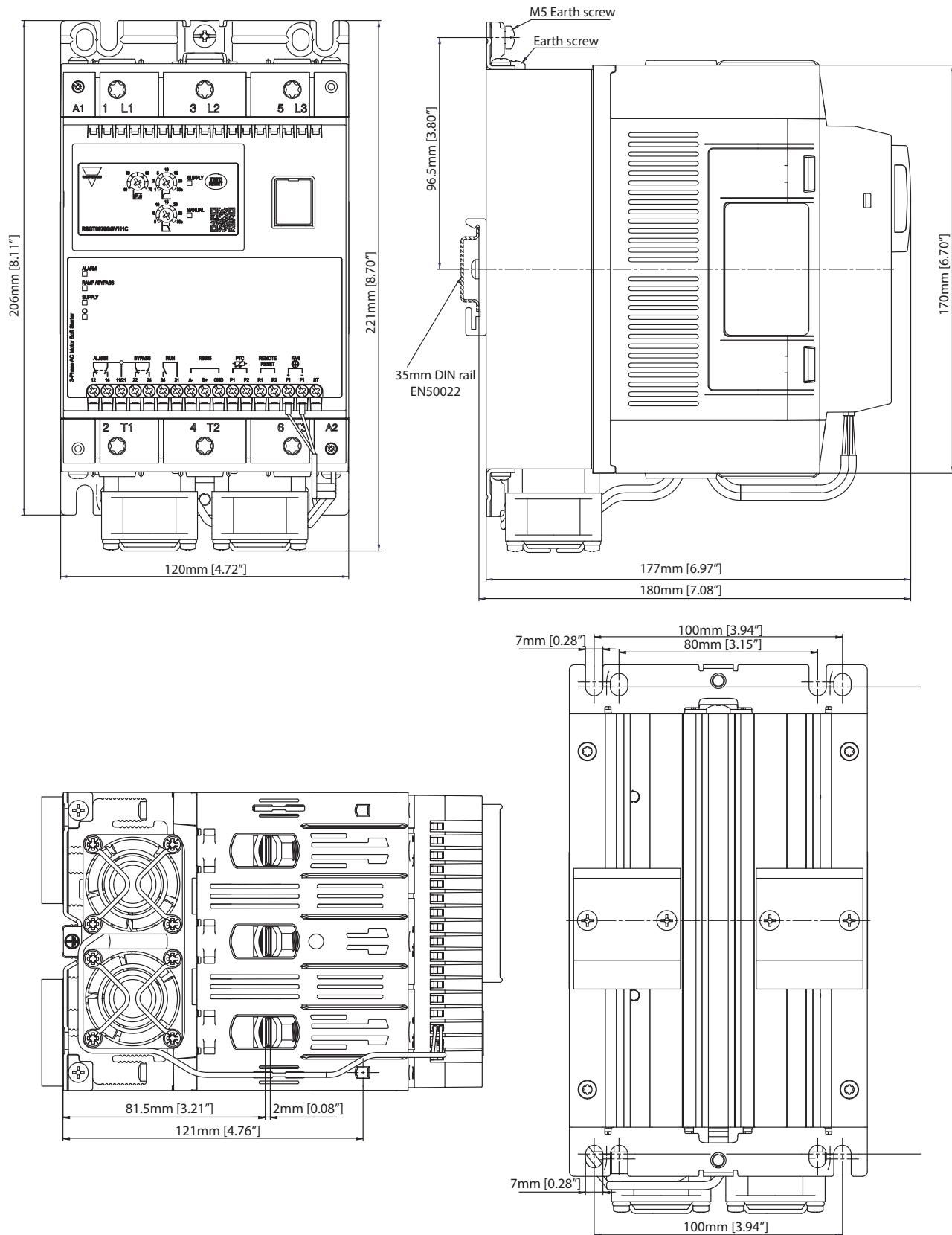


Fig. 2 RSGT 75mm: RSGT..32.. to RSGT..55



| **Fig. 3 RSGT 120mm: RSGT..70.. to RSGT..90**

 Power Supply

| | RSGT40 | RSGT60 |
|--------------------------------------|--------------------|------------------|
| Operational voltage range | 187 - 440 VACrms | 187 - 660 VACrms |
| Supply current at Idle | < 30 mAmps | |
| Blocking voltage | 1200 Vp | 1600 Vp |
| Rated AC frequency | 50/60 Hz (+/- 10%) | |
| Rated insulation voltage | 600 VAC | 690 VAC |
| Dielectric withstand voltage: | | |
| Supply to input | 2.5 kVrms | |
| Supply to heatsink | 2.5 kVrms | |
| Integrated varistor | Yes | |

 Inputs

| | RSGT40..E0V | RSGT40..F0V | RSGT60..FFV | RSGT60..GGV |
|--|---|--|-------------------------------------|---|
| Control voltage (Uc) | A1 - A2: 110 - 400 VAC +10%, -15% | A1 - A2: 24 VAC/VDC +10%, -10% | ST: 24 VAC/VDC +10%, -15% | ST: 100 - 240 VAC +10%, -15% |
| Control voltage range (Uc) | 93.5 - 440 VAC | 21.6 - 26.4 VAC/DC | 21.6 - 26.4 VAC/DC | 85 - 264 VAC |
| Maximum pick-up voltage | 80 VAC | 20.4 VAC/DC | 20.4 VAC/DC | 80 VAC |
| Minimum drop out voltage | 20 VAC | 5 VAC/DC | 5 VAC/DC | 20 VAC |
| Supply voltage range (Us) | - | - | A1 - A2: 24 VAC/DC +10%, -10% | A1 - A2: 100 - 240 VAC +10%, -15% |
| Rated AC frequency | 45 - 66 Hz | 45 - 66 Hz (applies to 24 VAC supply) | 45 - 66 Hz | 45 - 66 Hz |
| Rated insulation voltage (Ui) | | 500 VAC | | |
| Dielectric strength: | | | | |
| Dielectric withstand voltage | | 2 kVrms | | |
| Rated impulse withstand voltage | | 4 kVrms | | |
| Control input current | 0.55 - 1.3 mAmps | 0.4 - 1 mAmps | 0.5 - 1.5 mAmps | 0.4 - 3 mAmps |
| Input to output response time (Mains supply already present) | | 200 ms | | |
| Input to output response time (Mains supply applied with control) | 2 sec | | 3 sec | |
| Integrated varistor | Yes | | | |

Note 1: for the Canadian application, the control terminals A1, A2 (or A1, A2, ST for RSGT60 versions) of the RSGT devices shall be supplied by a secondary circuit where power is limited by a transformer, rectifier, voltage divider, or similar device that derives power from a primary circuit, and where the short-circuit limit between conductors of the secondary circuit or between conductors and ground is 1500VA or less. The short-circuit volt ampere limit is the product of the open circuit voltage and the short circuit ampere.

Note 2: RSGT60GG soft starters require a separate 100 - 240V, 50/60 Hz single phase control source, while RSGT60FF requires 21.6 - 26.4 VAC/DC. Output connections (L1, L2, L3, T1, T2, T3) are not galvanically isolated from the external supply connections (A1, A2, ST).

 **Outputs**

| | RSGT..12 | RSGT..16 | RSGT..25 |
|--|----------|---------------------|----------|
| Overload cycle @ 40°C surrounding temperature (acc. to EN/IEC 60947-4-2) | | AC53b: 3 - 12 : 288 | |
| Maximum number of starts/hr @ rated overload cycle @ 40°C surrounding temperature | | 12 | |
| Rated operational current @ 40°C | 12 Arms | 16 Arms | 25 Arms |
| Rated operational current @ 50°C | 12 Arms | 15 Arms | 23 Arms |
| Rated operational current @ 60°C | 12 Arms | 13 Arms | 21 Arms |
| Minimum load current | | 1 Arms | |

| | RSGT..32 | RSGT..45 | RSGT..55 |
|--|----------|---------------------|----------|
| Overload cycle @ 40°C surrounding temperature (acc. to EN/IEC 60947-4-2) | | AC53b: 3 - 12 : 288 | |
| Maximum number of starts/hr @ rated overload cycle @ 40°C surrounding temperature | | 12 | |
| Rated operational current @ 40°C | 32 Arms | 45 Arms | 55 Arms |
| Rated operational current @ 50°C | 29 Arms | 41 Arms | 50 Arms |
| Rated operational current @ 60°C | 27 Arms | 37 Arms | 46 Arms |
| Minimum load current | | 5 Arms | |

| | RSGT..70 | RSGT..90 |
|--|----------|---------------------|
| Overload cycle @ 40°C surrounding temperature (acc. to EN/IEC 60947-4-2) | | AC53b: 3 - 12 : 288 |
| Maximum number of starts/hr @ rated overload cycle @ 40°C surrounding temperature | | 12 |
| Rated operational current @ 40°C | 70 Arms | 90 Arms |
| Rated operational current @ 50°C | 64 Arms | 83 Arms |
| Rated operational current @ 60°C | 59 Arms | 76 Arms |
| Minimum load current | | 5 Arms |

Note: the overload cycle describes the switching capability of the soft starter at a surrounding temperature of 40°C as described in EN/IEC 60947-4-2. An overload cycle AC53b:3-12:348 means that the soft starter can handle a starting current of 3x Ie for 12 seconds followed by an OFF time of 348 seconds.

 **Auxiliary relays**

| | RSGT 45mm | RSGT 75mm | RSGT 120mm |
|-------------------------------------|---|--|------------|
| Number of output relays | 2 | | 3 |
| Function of relays | Alarm, Bypassed (top of ramp). | Alarm, Bypassed (top of ramp), Run | |
| Rated operational voltage | 250 VAC/30 VDC | | |
| Rated insulation voltage | 250 VAC | | |
| Dielectric withstand voltage | 2.5 kV | | |
| Overvoltage category | II | | |
| Type of control circuit | Electromechanical relay | | |
| Number of contacts | Alarm: 1 Bypassed: 1 | Alarm: 2 Bypassed: 2 Run: 1 | |
| Type of contacts | Alarm: normally closed (NC) Bypassed: normally open (NO) | Alarm: Changeover (NO, NC) Bypassed: Changeover (NO, NC) Run: Normally open (NO) | |
| Type of current | AC / DC | | |
| Rated operational current | 3 Arms @ 250 VAC, 3 Arms @ 30 VDC | | |

 **RS485**

| | |
|------------------------------------|---|
| Type | Bi-directional (static and dynamic variables and parameters) |
| Functions | Configuration of device Start/Stop Modification of set-point parameters Monitoring of measured variables |
| Connection | 2-wires Note: to reduce the noise use a shielded cable and connect the shield to GND terminal and to the ground at the same point. |
| Address | Default : 1 Selectable via software: range 1 - 247 |
| Protocol | MODBUS (RTU) |
| Factory defined data format | Data bits: 8 Parity: none Stop bit: 1 Selectable via software: parity: none (2 stop bits), odd (1 stop bit), even (1 stop bit) |
| Baud rate | Default: 9.6k bits/s Selectable via software: 9.6k, 19.2k, 38.4k bits/s |

Note: applies to RSGT...V.C models only

 **Environmental**

| | |
|------------------------------|--|
| Working temperature | -20°C to +60°C (-4°F to +140°F). Note: for temperatures > 40°C derating applies. |
| Storage temperature | -40°C to +80°C (-40°F to +176°F). |
| Relative humidity | < 95% non-condensing @ 40°C. |
| Pollution degree | 2 |
| Installation category | III |
| Installation altitude | 1000 m |
| Vibration | Acc. to IEC/EN 60068-2-6 |
| Frequency 1 | 2 [+3/-0] Hz to 25 Hz displacement +/- 1.6 mm |
| Frequency 2 | 10 Hz to 55 Hz @ 2g (19.96m/s ²) @ constant displacement |

 **Compatibility and conformity**

| | |
|-----------------------------|---|
| Approvals |     |
| Standards compliance | <p>RSGT 45 mm</p> <p>LVD: EN 60947-4-2:2012 EE: EN 60947-4-2:2012 EMCD: EN 60947-4-2:2012 EMC: EN 60947-4-2:2012 UL: UL 60947-4-2, E172877, NMFT cUL: C22.2 no. CSA C22.2 no. 60947-4-2, E172877, NMFT7</p> <p>RSGT 75 mm / RSGT 120 mm</p> <p>LVD: EN 60947-4-2:2012 EE: EN 60947-4-2:2012 EMCD: EN 60947-4-2:2012 EMC: EN 60947-4-2:2012 UL: E172877, NMFT, UL508 cUL: C22.2 no. CSA C22.2 no. 14, E172877, NMFT7</p> |

| Electromagnetic compatibility (EMC) - immunity | | | |
|---|---|--|--|
| | RSGT 45 mm | RSGT 75 mm | RSGT 120 mm |
| Electrostatic discharge (ESD) EN/IEC 61000-4-2 8 kV air discharge, 4 kV contact | PC1 | PC2 | PC2 |
| Radiated radio frequency EN/IEC 61000-4-3 10 V/m, from 80 MHz to 1 GHz 10 V/m, from 1.4 to 2 GHz 3 V/m, from 2 to 2.7 GHz | | PC1 PC1 PC1 | |
| Electrical fast transient (burst) EN/IEC 61000-4-4 AC input: 2 kV, 5 kHz & 100 kHz DC input: 1 kV, 5 kHz & 100 kHz Signal: 1 kV, 5 kHz & 100 kHz Control: 2 kV, 5 kHz & 100 kHz Output: 2 kV, 5 kHz & 100 kHz | PC1 PC2 PC2 PC2 PC2 | PC2 PC2 PC2 PC2 PC1 | PC2 PC2 PC2 PC2 PC2 |
| Conducted radio frequency EN/IEC 61000-4-6 10 V/m, from 0.15 to 80 MHz | | PC2 | |
| Electrical surge, EN/IEC 61000-4-5 Output, line to line: 1 kV Output, line to earth: 2 kV AC input, line to line: 1 kV AC input, line to earth: 2 kV DC input, line to line: 1 kV DC input, line to earth: 2 kV Signal and control, line to earth: 2 kV | PC2 PC1 PC1 PC1 PC2 PC2 PC1 | PC2 PC2 PC1 PC1 PC2 PC2 1 kV (PC2) | PC2 PC2 PC1 PC1 PC2 PC2 1 kV (PC2) |
| Voltage dips, EN/IEC 61000-4-11 0% for 10 ms and 20 ms 40% for 100, 200, 1000 ms 70% for 500 ms 80% for 5000 ms 0% for 5000 ms | | PC2 PC2 PC2 PC2 PC2 | |

| Electromagnetic compatibility (EMC) - emissions | |
|---|---|
| Radio interference field emission (radiated) | EN/IEC 55011 Class A (Industrial): from 30 to 1000 MHz |
| Radio interference voltage emissions (conducted) | EN/IEC 55011 Class A (Industrial): from 0.15 to 30 MHz |

Performance

► Current / power ratings: kW and HP @ 40°C

| Model | IEC Rated Current | 220 - 240 VAC | 380 - 415 VAC | 440 - 480 VAC | 550 - 600 VAC |
|-----------------|-------------------|-----------------|-----------------|-----------------|---------------|
| RSGT..12 | 12 Arms | 3 kW / 3 HP | 5.5 kW / 5 HP | 5.5 kW / 7.5 HP | 9 kW / 10 HP |
| RSGT..16 | 16 Arms | 4 kW / 5 HP | 7.5 kW / 7.5 HP | 9 kW / 10 HP | 11 kW / 15 HP |
| RSGT..25 | 25 Arms | 5.5 kW / 7.5 HP | 11 kW / 10 HP | 11 kW / 15 HP | 20 kW / 20 HP |
| RSGT..32 | 32 Arms | 9 kW / 10 HP | 15 kW / 15 HP | 18.5 kW / 20 HP | 22 kW / 30 HP |
| RSGT..45 | 45 Arms | 11 kW / 15 HP | 22 kW / 25 HP | 22 kW / 30 HP | 37 kW / 40 HP |
| RSGT..55 | 55 Arms | 15 kW / 20 HP | 30 kW / 30 HP | 30 kW / 40 HP | 45 kW / 50 HP |
| RSGT..70 | 70 Arms | 20 kW / 25 HP | 37 kW / 40 HP | 45 kW / 50 HP | 55 kW / 60 HP |
| RSGT..90 | 90 Arms | 22 kW / 30 HP | 45 kW / 50 HP | 45 kW / 60 HP | 55 kW / 75 HP |

Ratings:

kW rating according to: IEC/EN 60947-4-2

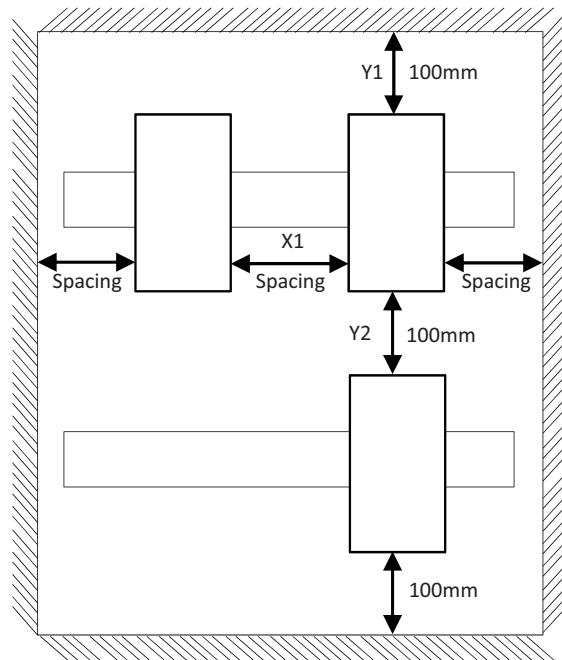
► Starts per hour

The table below indicates the maximum number of starts/hr that can be done by the different RSGT models at different operating currents with a surrounding temperature of 40°C.

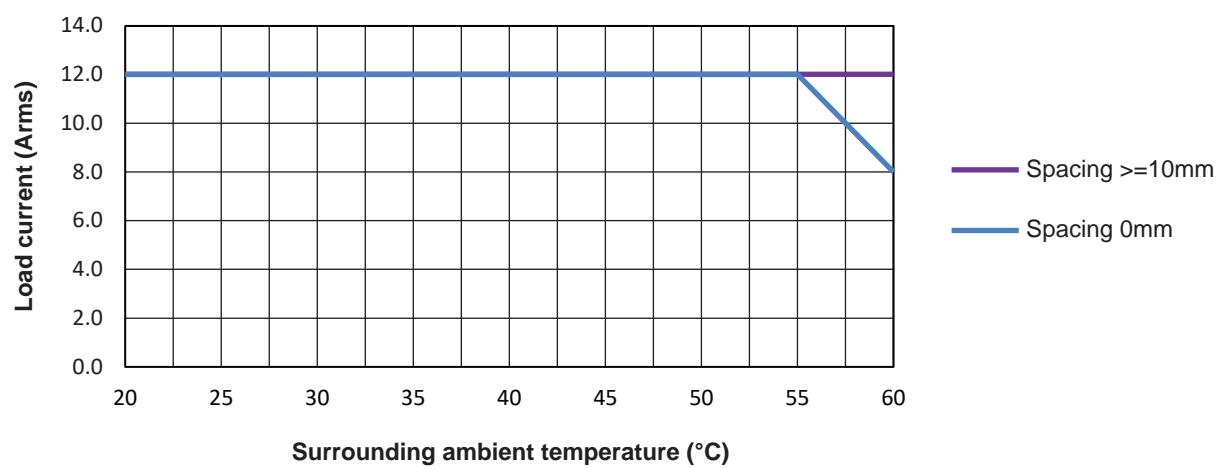
| Model | Operational current | | | |
|------------------|---------------------|---------|---------|---------|
| | 6 Arms | 12 Arms | 16 Arms | 25 Arms |
| RSGT..12. | 26 | 12 | - | - |
| RSGT..16. | 37 | 17 | 12 | - |
| RSGT..25. | 64 | 29 | 21 | 12 |

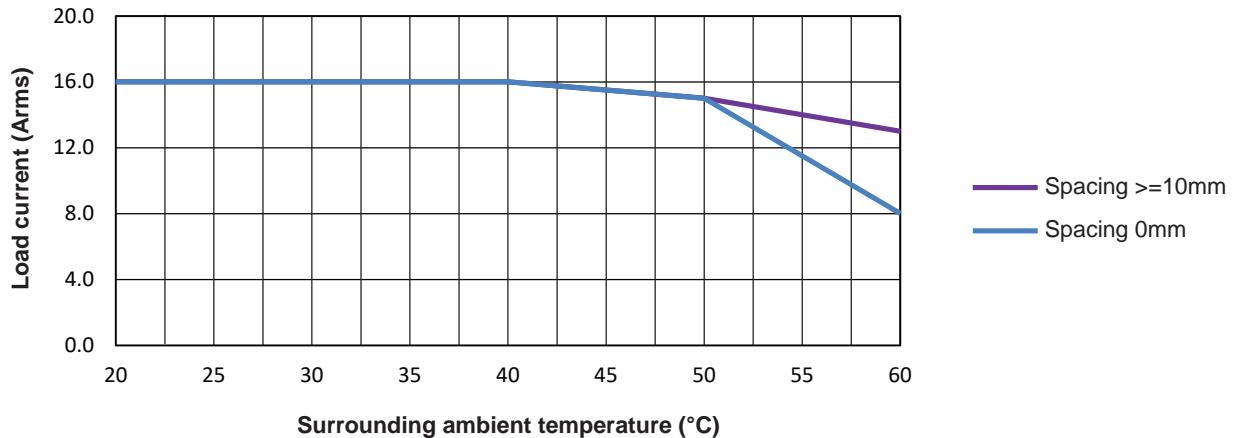
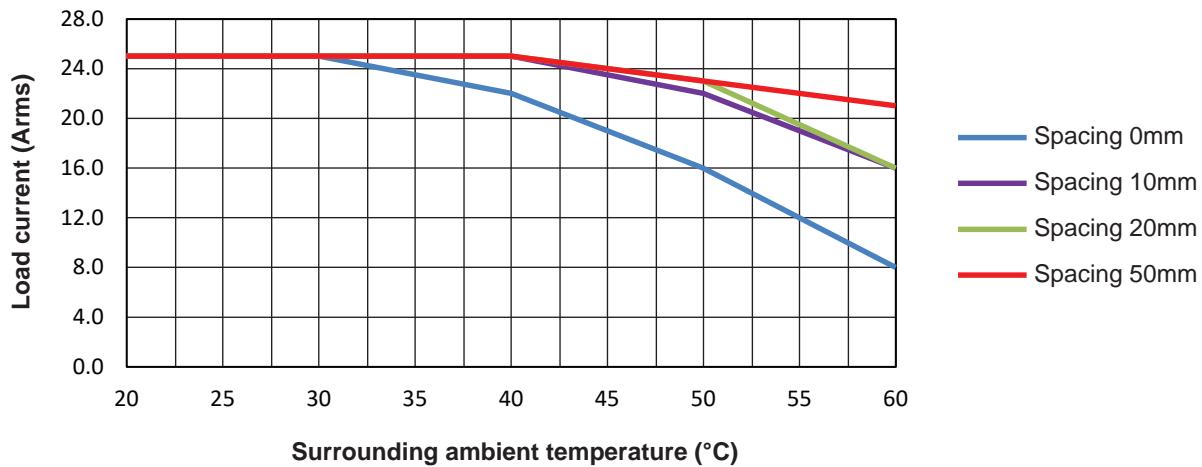
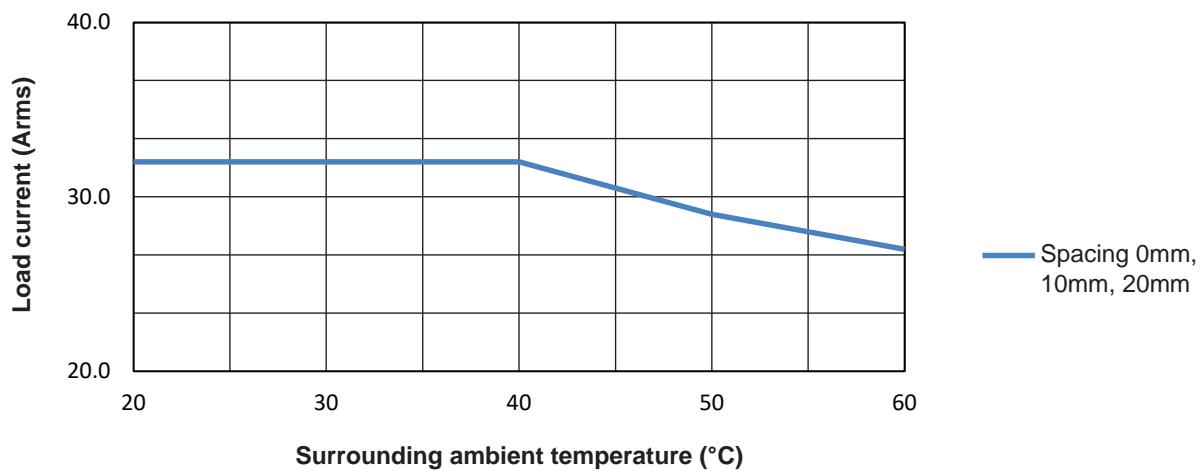
| Model | Operational current | | | | | | | |
|------------------|---------------------|---------|---------|---------|---------|---------|---------|---------|
| | 12 Arms | 16 Arms | 25 Arms | 32 Arms | 45 Arms | 55 Arms | 70 Arms | 90 Arms |
| RSGT..32. | 36 | 26 | 12 | - | - | - | - | - |
| RSGT..45. | 55 | 40 | 24 | 18 | 12 | - | - | - |
| RSGT..55. | 75 | 54 | 32 | 24 | 16 | 12 | - | - |
| RSGT..70 | 90 | 66 | 41 | 31 | 21 | 16 | 12 | - |
| RSGT..90 | 121 | 89 | 55 | 42 | 28 | 22 | 17 | 12 |

► Current derating curves

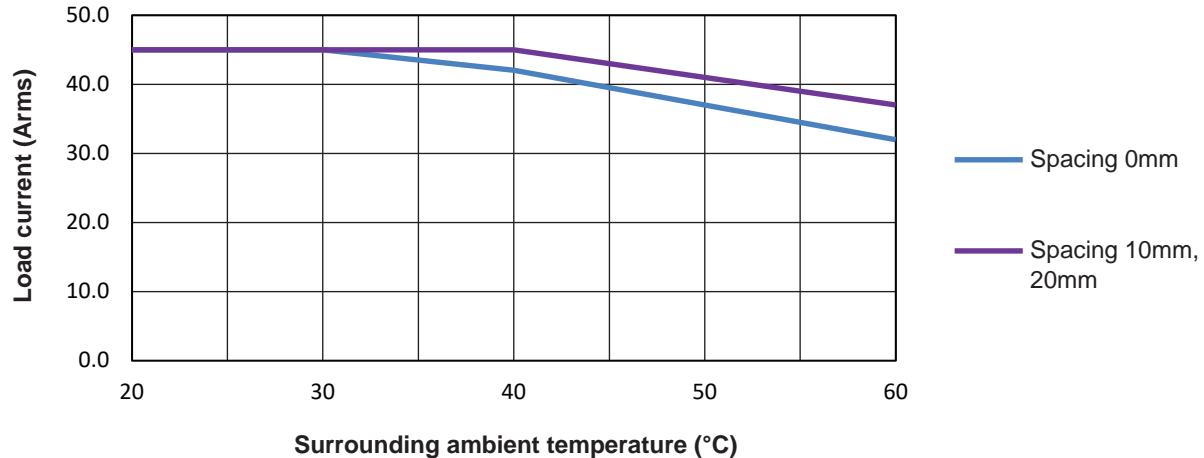


RSGT..12

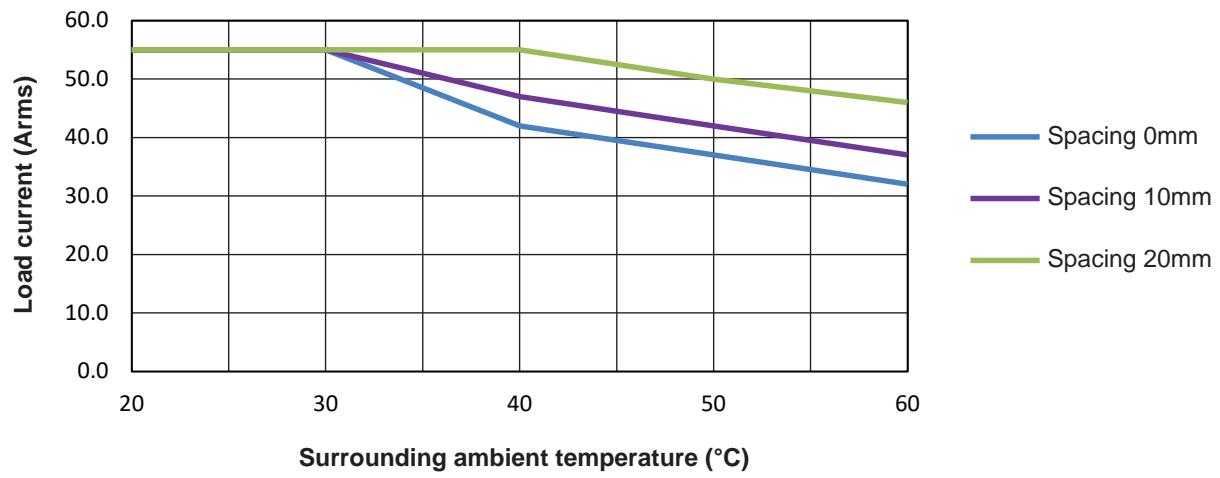


RSGT..16

RSGT..25

RSGT..32


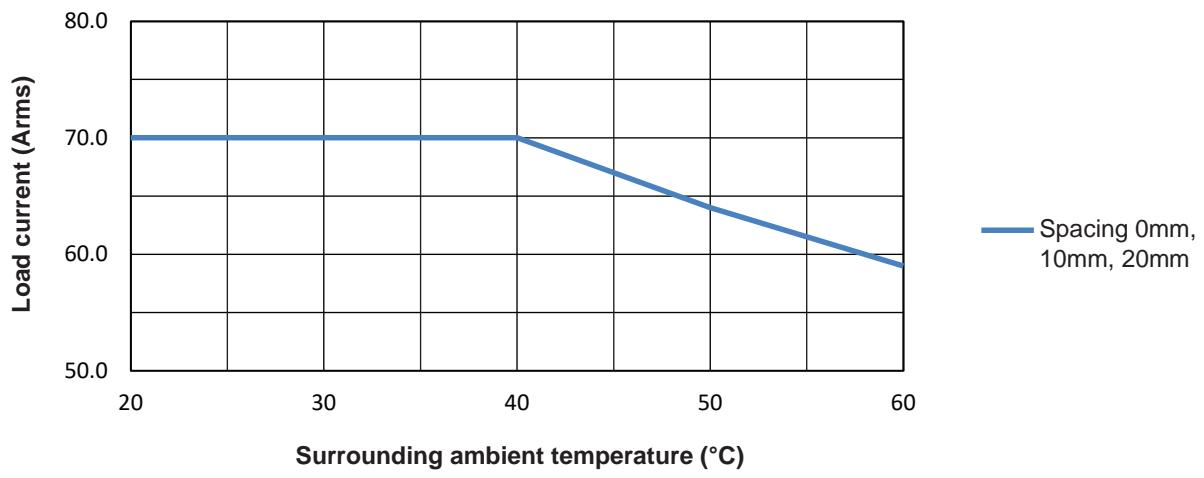
RSGT..45



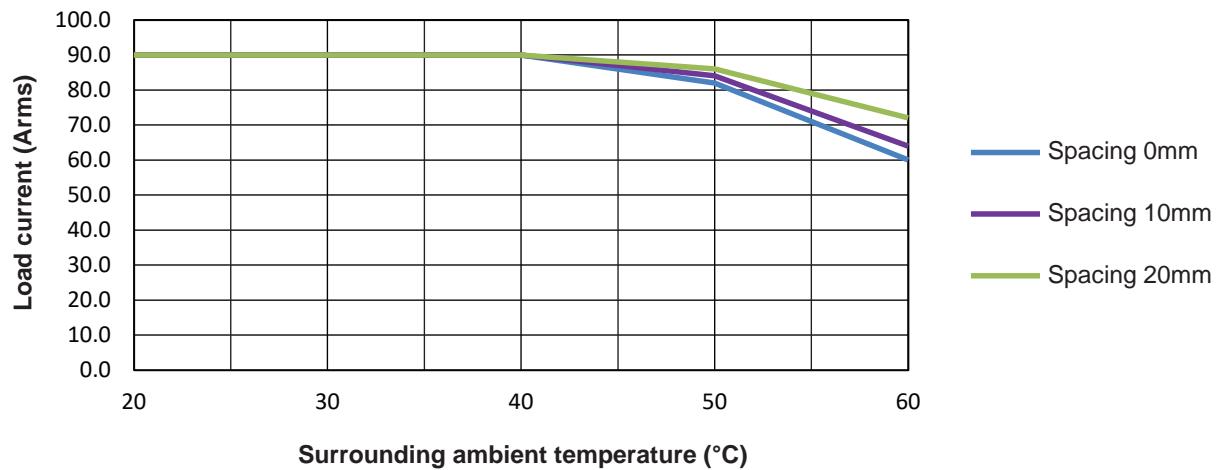
RSGT..55



RSGT..70



RSGT..90



Connection Diagrams

Terminal markings

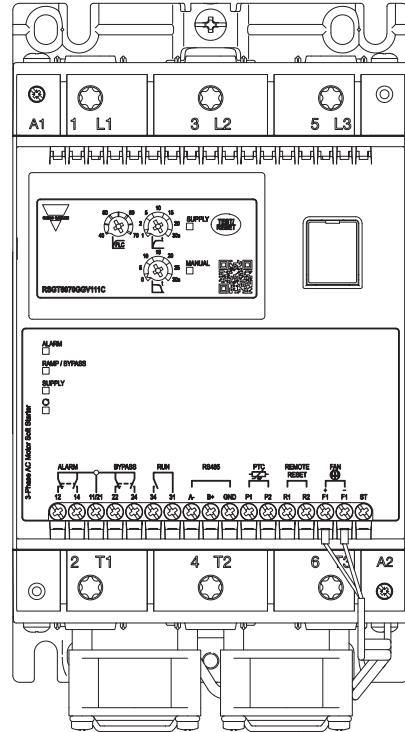
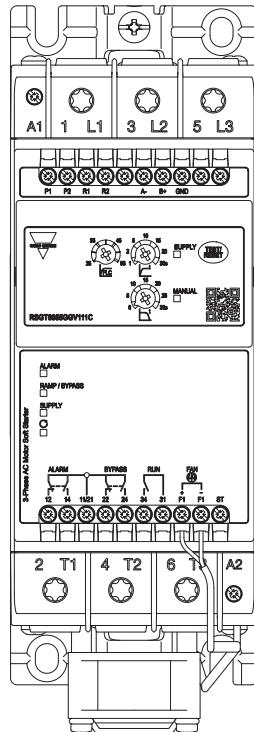
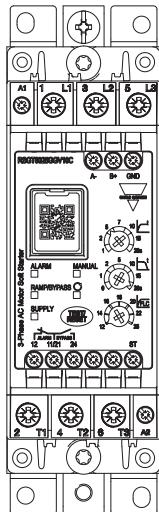
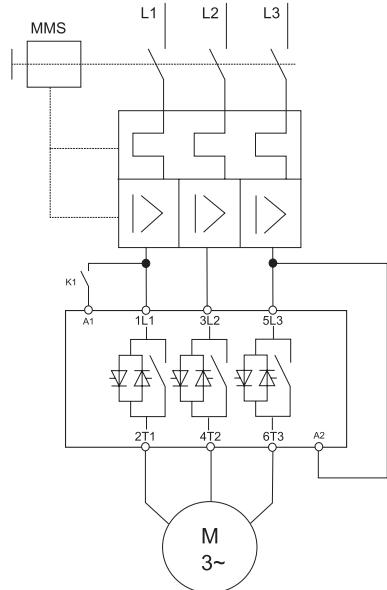
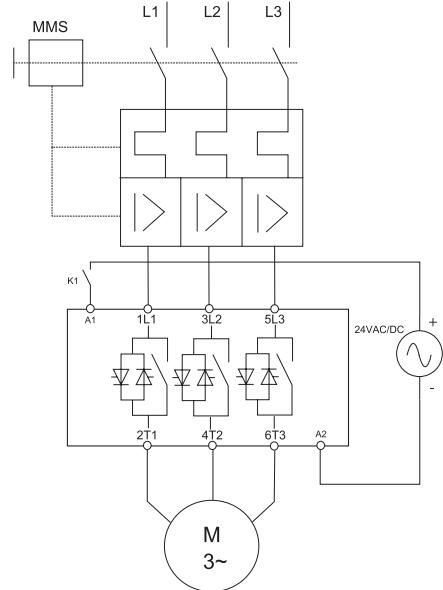
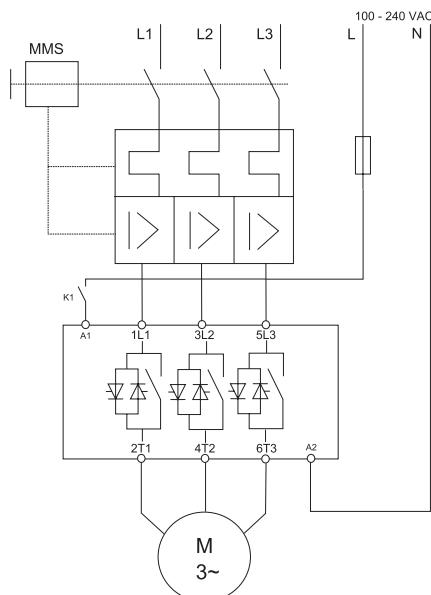
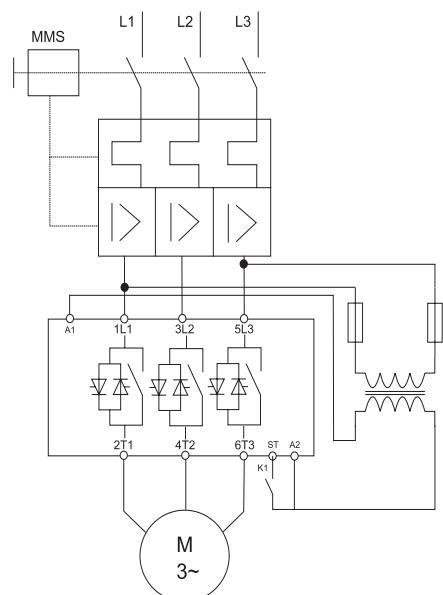


Fig. 4 RSGT 45mm...

Fig. 5 RSGT 75mm...

Fig. 6 RSGT 120mm...

| Marking | RSGT 45 mm | | RSGT 75mm | | RSGT 120mm | |
|------------------|--|--|-----------------|-----------------|-----------------|----------------|
| | RSGT40 | RSGT60 | RSGT40 | RSGT60 | RSGT40 | RSGT60 |
| 1 L1, 3 L2, 5 L3 | Line connections | | | | | |
| 2 T1, 4 T2, 6 T3 | Load connections | | | | | |
| A1, A2 | Control voltage | Supply voltage | Control voltage | Supply voltage | Control voltage | Supply voltage |
| ST | - | Control voltage | - | Control voltage | - | |
| 11, 12 | Alarm indication (normally closed, NC) | | | | | |
| 21, 22 | - | Top of ramp indication (normally closed, NC) | | | | |
| 21, 24 | Top of ramp indication (normally open, NO) | | | | | |
| 31, 34 | - | Run relay (normally open, NO) | | | | |
| R1, R2 | - | Remote reset of alarms | | | | |
| P1, P2 | - | PTC input | | | | |
| A-, B+, GND | Modbus connections ** | | | | | |
| F1+, F1- * | - | Fan connection | | | | |
| Note: | For the 24 VDC (RSGT40..F0, RSGT60..FF) models: Connect A1 to the positive (+) and A2 to the negative (-) terminal. | | | | | |

 **Wiring diagrams**

Fig. 7 RSGT40E0...

Fig. 8 RSGT40F0...

Fig. 9 RSGT40E0...

Fig. 10 RSGT60.
*GG models: Apply 100 - 240VAC,
FF models: Apply 24VAC/DC*

*Note : It is recommended that the power factor correction capacitors be switched out of the circuit during the ramp-up phase. When the RSGT is in the bypass state (bypass relays closed), the capacitor may be switched back into the circuit. Capacitors may affect the proper operation of the silicon controlled rectifiers (SCRs) if kept in the circuit during the start ramp.


Connection specifications

| Line conductors 1 L1, 3 L2, 5 L3, 2 T1, 4 T2, 6 T3 Acc. to EN60947-1 | | | |
|---|---|------------|---|
| | RSGT 45mm | RSGT 75 mm | RSGT 120 mm |
| Flexible | 2.5 - 10 mm ² 2.5 - 2 x 4 mm ² | | - |
| Rigid (solid or stranded) | 2.5 - 10 mm ² | | 2 x (10 - 50 mm ²) |
| Flexible with end sleeve (ferrule) | 2.5 - 10 mm ² | | 2 x (10 - 50 mm ²) |
| UL/cUL rated data Rigid (stranded) Rigid (solid) Rigid (solid or stranded) | AWG 6 -14 AWG 10 -14 2 x (AWG 10 - 14) | | 2 x (AWG 8 - 10) |
| Terminal screws | M4 | | M8 |
| Maximum tightening torque | 2.5 Nm (22 lb.in) with pozidriv bit 2 | | 12 Nm (106 lb.in) with Torx TT40 bit |
| Stripping length | 8.0 mm | | 20 mm |

| Secondary conductors A1, A2 Acc. to EN60998 | | | |
|--|-----------|--|-------------|
| | RSGT 45mm | RSGT 75 mm | RSGT 120 mm |
| Flexible | | 0.5 1.5 mm ² | |
| Rigid (solid or stranded) | | 0.5 2.5 mm ² | |
| Flexible with end sleeve (ferrule) | | 0.5 1.5 mm ² | |
| UL/cUL rated data Rigid (solid or stranded) | | AWG 10...18 | |
| Terminal screws | | M3 | |
| Maximum tightening torque | | 0.6 Nm (5.3 lb.in) with pozidriv bit 1 | |
| Stripping length | | 6.0 mm | |

| Auxiliary conductors 11, 12, 21, 22, 24, ST, A-, B+, GND, P1, P2, R1, R2, F1+, F1- | | | |
|---|-----------|------------------------------------|-------------|
| | RSGT 45mm | RSGT 75 mm | RSGT 120 mm |
| Rigid (solid or stranded) | | 0.5 ... 2.5 mm ² | |
| Flexible with end sleeve (ferrule) | | 0.05 ... 1.5 mm ² | |
| UL/cUL rated data Rigid (solid or stranded) | | AWG 30 ... 14 | |
| Terminal screws | | M3 | |
| Maximum tightening torque | | 0.45 Nm (4.0 lb.in) pozidriv bit 1 | |
| Stripping length | | 6.0 mm | |

Use 75°C Copper (Cu) conductors

Troubleshooting

► LED status indications

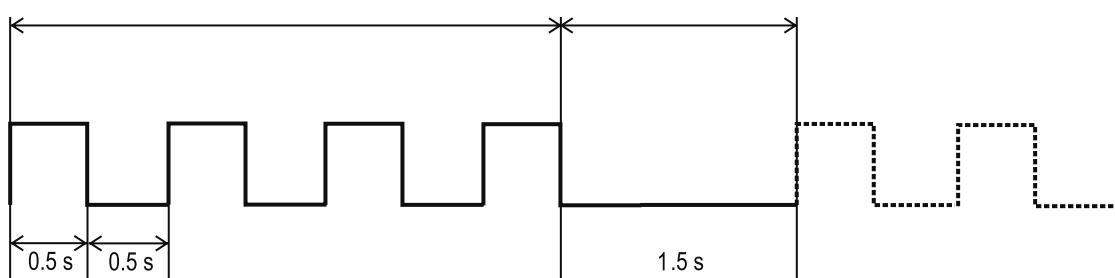
| State | Supply (green LED) | Ramp/Bypass (yellow LED) | Alarm (red LED) | Manual (yellow LED) |
|--|-----------------------|-----------------------------|--------------------|------------------------|
| Idle | ON | OFF | OFF | OFF/ON |
| Ramping | ON | Flashing | OFF | OFF/ON |
| Bypass | ON | ON | OFF | OFF/ON |
| Alarm (Auto-recovery) | ON | OFF | Flashing | OFF |
| Alarm (Manual recovery) | ON | OFF | Flashing | ON |
| Internal fault | ON | OFF | ON | OFF/ON |
| Idle (Start to start or stop to start time not elapsed) | Flashing | OFF | OFF | OFF/ON |

► Relay status indication

| State | Supply (green LED) | Relay contact position | | | | |
|--|-----------------------|------------------------|--------------------|------------------------|------------------------|-----------------|
| | | RSGT 45mm | | RSGT 75mm, RSGT 120 mm | | |
| | | Alarm (11, 12) | Bypass (21, 24) | Alarm (11, 12, 14) | Bypass (21, 22, 24) | Run (31, 34) |
| Idle | ON | Closed | Open | 11, 12 | 21, 22 | Open |
| Ramping | ON | Closed | Open | 11, 12 | 21, 22 | Closed |
| Bypass | ON | Closed | Closed | 11, 12 | 21, 24 | Closed |
| Alarm (Auto-recovery) | ON | Open | Open | 11, 14 | 21, 22 | Open |
| Alarm (Manual recovery) | ON | Open | Open | 11, 14 | 21, 22 | Open |
| Internal fault | ON | Open | Open | 11, 14 | 21, 22 | Open |
| Idle (Start to start or stop to start time not elapsed) | Flashing | Closed | Open | 11, 12 | 21, 22 | Open |

► Alarms

The RSGT includes a number of diagnostics and protection features each of which is signalled through a flashing sequence on the red LED.



| | |
|--|--|
| Number of flashes | 2 |
| Alarm | Wrong phase sequence |
| Alarm description | If the connection to the soft starter is not done in the correct sequence (L1, L2, L3), the RSGT will trigger the wrong phase sequence alarm and the motor will not be started. |
| Alarm recovery period | N/A |
| Consecutive alarms for hard reset | 1 |
| Action to recover alarm | <p>User intervention is required to change the wiring sequence to recover alarm. Note: the phase sequence monitoring can be disabled. To disable the alarm, refer to the "Structure" section</p> <p>ATTENTION: in this mode, if the wiring is not in the correct sequence, the motor will rotate in the reverse direction.</p> |
| Troubleshooting | <ul style="list-style-type: none"> Check that wiring on L1, L2, L3 is in the correct sequence. If you need to reverse the motor, make sure that the phase sequence LED is ON (phase sequence protection disabled). |

| | |
|--|--|
| Number of flashes | 3 |
| Alarm | Line voltage out of range |
| Alarm description | <p>At every power-up the RSGT automatically detects the supply voltage level and determines whether it is working on a 220, 400, 480* or 600* V supply. The under- or over- voltage alarm level is then set at a level of -20% and +20% (from the measured supply voltage level) respectively.</p> <p>If the supply voltage level is out of these limits for more than 5 seconds then the line voltage out of range alarm will be triggered.</p> <p>* Applies to RSGT60 models.</p> <p>Note: for RSGT60 over-voltage alarm level (for the case of a 600V supply) is 675V (600V + 12.5%).</p> |
| Alarm recovery period | 5 minutes |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | <p>The alarm will self-recover (in auto-recovery mode) after 5 minutes from when the supply voltage is within limits.</p> <p>(If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section).</p> |
| Troubleshooting | <ul style="list-style-type: none"> Check supply voltage level across L1, L2, L3 terminals. Make sure that you are not using a RSGT40 model on a supply voltage > 440 VAC. |

| | |
|--|--|
| Number of flashes | 4 |
| Alarm | Phase loss (motor side) |
| Alarm description | <p>If any of the phases on the load (motor) side becomes open the RSGT will trip after 5 seconds to protect the motor from running/ starting on 2 phases.</p> <p>Note: this alarm will also be triggered when a current unbalance of > 20% is detected on any of the three line currents for a minimum of 5 secs. Additionally if a SCR and/or bypass relay is open (damaged) the same alarm will be triggered.</p> |
| Alarm recovery period | 5 minutes |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | <p>Check connections on the output side of the soft starter and on the motor terminals. The alarm will self-recover (in Auto-recovery mode) after 5 minutes.</p> <p>(If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section).</p> |
| Troubleshooting | <ul style="list-style-type: none"> Check for any loose connections on the T1, T2, T3 side of the soft starter. Check for any loose connections on the motor terminals. Check motor windings. |

| | |
|--|---|
| Number of flashes | 5 |
| Alarm | Locked rotor |
| Alarm description | If a current $\geq 5 \times \text{FLC}$ setting for 100 msec is detected, the RSGT will issue the locked rotor alarm. |
| Alarm recovery period | 5 minutes |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | The alarm will self-recover (in Auto-recovery mode) after 5 minutes. (If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section). |
| Troubleshooting | <ul style="list-style-type: none"> • Check that FLC setting is not smaller than motor name plate current. • Check that the RSGT model is suitably rated for the motor. • Check motor windings resistance to check if motor is damaged. |

| | |
|--|--|
| Number of flashes | 6 |
| Alarm | Dry-run |
| Alarm description | If less than 50% of FLC current flows for 5 seconds, dry-run alarm will be triggered. |
| Alarm recovery period | 5 minutes |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | The alarm will self-recover (in Auto-recovery mode) after 5 minutes (If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section). |
| Troubleshooting | <ul style="list-style-type: none"> • Check that the FLC setting is not too much higher than the motor name plate current. • Check motor load. |

| | |
|--|---|
| Number of flashes | 7 |
| Alarm | Over-temperature |
| Alarm description | The RSGT constantly measures the heatsink and thyristors (SCRs) temperature. If the maximum internal temperature is exceeded (for 0.5 sec) an over-temperature alarm is triggered. This condition can be triggered by too many starts per hour, an over-load condition during starting and/or stopping or a high surrounding temperature. |
| Alarm recovery period | Depends on the cooling period. The RSGT will only recover if the internal temperature is within safe limits. |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | The alarm will self-recover (in Auto-recovery mode) - the recovery period will depend on the cooling time required by RSGT. The higher the surrounding temperature, the longer the cooling period. (If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section). |
| Troubleshooting | <ul style="list-style-type: none"> • Check that the specified number of starts/hr are not exceeded. • Check that the surrounding temperature around the soft starter is within limits. |

| | |
|--|---|
| Number of flashes | 8 |
| Alarm | Overload |
| Alarm description | The overload alarm can be triggered in case of the following conditions: Measured current > 1.05 x FLC during transition from ramp-up to bypass and also during bypass. Load current > FLC. Trip time will vary according to Trip Class 10. |
| Alarm recovery period | Depends on the cooling period. To disable class 10 overload protection follow the instructions in the "Structure" section. The RSGT will only recover if the internal temperature is within safe limits. |
| Consecutive alarms for hard reset | 5 |
| Action to recover alarm | The alarm will recover automatically after (approx.) 5 minutes. (If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section). Note: allow enough time for the motor to cool before attempting the next start. |
| Troubleshooting | <ul style="list-style-type: none"> Make sure that the FLC setting is according to the current on the motor name plate. Check for any blockages in the load. If overload alarm occurs during ramp-up try to set a shorter ramp-up time or increase the FLC setting. |

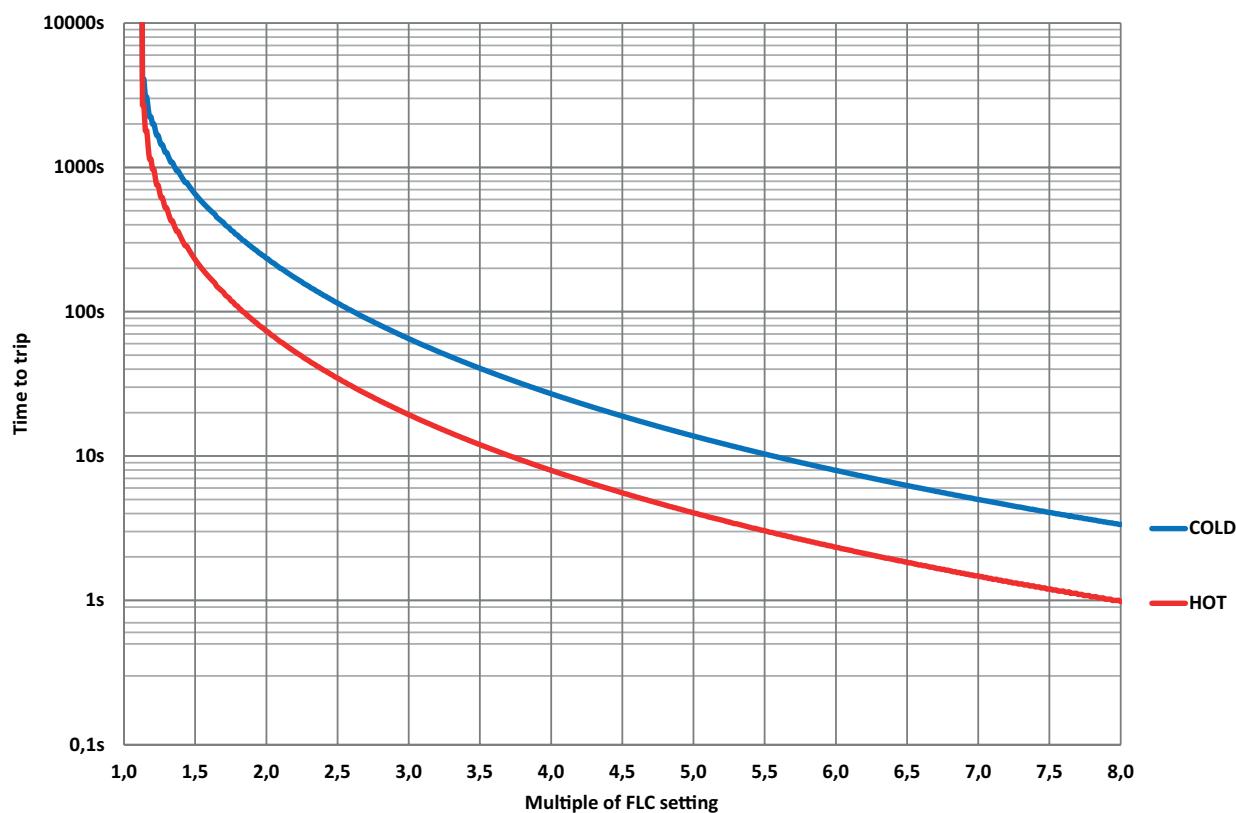


Fig. 11 RSGT Class 10 motor overload trip profile

| PTC resistance - P1, P2 connection * | | |
|--------------------------------------|---------|--|
| < 500Ω | No Trip | Normal running |
| > 1000Ω | Trip | Overload alarm (8 flashes) & alarm relay activated |
| < 300Ω | Reset | |

| | |
|---|---|
| Remote reset of alarms (R1, R2)* | To reset alarms via the R1-R2 terminals you need to: Make sure that the alarm reset mode is set to MANUAL (MANUAL LED ON). To set the alarm reset mode to MANUAL press the Test/Reset button for 5 seconds when the RSGT is in IDLE mode. When RSGT is in alarm mode, short the terminals R1, R2 for 1 second. This will clear the alarm and RSGT will go to IDLE state. Note: do not apply voltage on R1, R2 terminals as this might damage the soft starter. |
|---|---|

| | |
|--|---|
| Number of flashes | 9 |
| Alarm | Supply voltage unbalance |
| Alarm description | The RSGT measures the voltages on all the three phases and if there is a difference of more than 20% for ≥ 5 sec between any of the phases, the RSGT will trigger the voltage unbalance alarm. |
| Alarm recovery period | 5 minutes |
| Consecutive alarms for hard reset | 4 |
| Action to recover alarm | The alarm will recover automatically after 5 minutes. (If manual reset mode is applied, alarm can be cleared as instructed in the "Structure" section). |
| Troubleshooting | <ul style="list-style-type: none"> Check supply voltage level across L1, L2, L3 terminals. Check connections on the L1, L2, L3 terminals. |

| | |
|--|---|
| Number of flashes | 10 |
| Alarm | Shorted thyristor (SCR) |
| Alarm description | In case the RSGT detects that there is a damaged (shorted) thyristor (SCR) on any of the three phases, the soft starter will trip. |
| Alarm recovery period | - |
| Consecutive alarms for hard reset | 1 |
| Action to recover alarm | Note: this alarm is not resettable and it is suggested to replace the unit and contact a Carlo Gavazzi representative should this alarm occur. |
| Troubleshooting | <ul style="list-style-type: none"> Check resistance across L1-T1 and L3-T3 to check for any short. If any of the SCRs is damaged, replace the soft starter. |

| | |
|--|---|
| Number of flashes | Fully ON |
| Alarm | Internal fault |
| Alarm description | In case there is an internal fault in the RSGT circuitry, the Red LED will remain continuously ON. |
| Alarm recovery period | - |
| Consecutive alarms for hard reset | 1 |
| Action to recover alarm | Note: this alarm is not resettable and it is suggested to replace the unit and contact a Carlo Gavazzi representative should this alarm occur. |
| Troubleshooting | <ul style="list-style-type: none"> Check resistance across L1 - T1 and L3 - T3 to check for any short. If any of the SCRs is damaged, replace the soft starter. |

* Applies to RSGT 75/120 mm models only

Short circuit protection

Type 1 protection implies that after a short circuit, the device under test will no longer be in a functioning state. The product variants listed in the table hereunder are suitable for use on a circuit capable of delivering not more than 5,000* symmetrical Amperes, 400 or 600 Volts maximum when protected by fuses. Tests at 5,000 A* were performed with Class RK5 fuses, fast acting; please refer to the table below for maximum allowed ampere rating of the fuse. Use fuses only.

* For RSGT 70 to RSGT 90 models 10,000 symmetrical Amperes apply.

Note: For fuse size of 600A or less, Class CC, G, H, K, J, RK1 or T fuses can be used instead of RK5 fuses.

► Time delay fuses (UL 60947-4-2)

| Item No. | Max. fuse size [A] | Current [kA] | Class | Max. voltage [VAC] | | |
|----------|--------------------|--------------|-------|--------------------|--|--|
| RSGT..12 | 15 | 5 | RK5 | 600 | | |
| RSGT..16 | 20 | | | | | |
| RSGT..25 | 25 | | | | | |
| RSGT..32 | 50 | | | | | |
| RSGT..45 | 50 | | | | | |
| RSGT..55 | 60 | | | | | |
| RSGT..70 | 100 | 10 | | | | |
| RSGT..90 | | | | | | |

► Manual motor starters

| Item No. | Model No. | Current [kA] | Max. voltage [VAC] |
|----------|-------------|--------------|--------------------|
| RSGT..12 | GMS32H-17 | 10 | 400 |
| RSGT..16 | GMS32H-17 | | |
| RSGT..25 | GMS32H-32 | | |
| RSGT..32 | GMS32H-32 | | |
| RSGT..45 | GMS63H-50 | | |
| RSGT..55 | GMS63H-63 | | |
| RSGT..70 | GMS100H-75 | | |
| RSGT..90 | GMS100H-100 | | |

Note: products protected with manual motor starters must be wired with a minimum length of 2.0 m (10.0 m for 12, 16 A models) of Cu wire conductor with a maximum cross-sectional area of 2.5 mm² for 12 Arms and 16 Arms devices, 10 mm² for 25, 32, 45 Arms devices, 16 mm² for 55 Arms devices and 50 mm² for higher currents. The length includes the conductors from the voltage source to the manual motor starter to the soft starter and from the soft starter to the load.



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